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A COMPUTER CONTROL SYSTEM FOR THE ALTERNATING GRADIENT
MAGNETOMETER

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ABSTRACT

An alternating gradient magnetometer has been interfaced to a computer for the automation of data taking. Using a fast Fourier transform analysis system data can be acquired and processed in real time. Data is stored on disk and can be recalled for plotting and further analysis. With the addition of a simple liquid nitrogen cryostat, magnetization measurements can be carried out in the range from 300 K to 77K. Results are reported on three different types of piezoelectric transducers.

Acknowledgements

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Introduction

The discovery of the ceramic superconductor Y-Ba-Cu-O ¹ and its related compounds has led to a renewed interest in the general field of superconductivity. The ceramic superconductors, which have transition temperatures ranging from 90K to 120K and perhaps higher²⁻⁴ have given rise to expectations of great technological utility. Unfortunately, most of these materials have low critical currents, which limits their current carrying abilities. This is a serious drawback for applications involving superconducting magnets and power transmission and storage.

In order to understand the limitations to the critical current it is important to be able to characterize the magnetic properties of a superconductor, as the two are intimately related⁵. Measurements of magnetization and magnetic hysteresis allow one to determine the extent of magnetic flux pinning, which is related to the microscopic critical current.

In the current research an alternating gradient magnetometer, which was constructed in the Summer of 1988, was interfaced with a computer in order to automate the taking of magnetization data.

Objectives

The objectives of this experiment were to interface the alternating gradient magnetometer to a computer and to write the program which would automate data taking. The program must be capable of reading the magnetization, temperature, and applied magnetic field, in real time, and storing them on a disk for later analysis.

Theory

The internal magnetic field in a non-ferromagnetic material is described by the equation

$$B = H + 4\pi M \quad (\text{cgs units})$$

where B is the magnetic induction, H is the external applied field and M is the magnetization. For homogeneous paramagnetic and diamagnetic materials M is a linear function of H . Thus, in a homogeneous material $M = XH$, where X is the magnetic susceptibility. In a paramagnetic material X is positive and in a diamagnetic material it is negative. Superconductors are diamagnetic when in the superconducting state and (usually) paramagnetic or non-magnetic ($X=0$) in the normal state. So a graph of M as a function of H should yield a straight line of slope X . In a superconductor, this will be true as long as the applied field does not approach the lower critical field H_{c1} . Once H_{c1} is exceeded, magnetic flux begins to penetrate the sample, in the form of quantized flux lines. These flux lines become pinned in the sample, reducing the diamagnetic magnetization. The presence of pinned flux, therefore, produces a hysteresis in the magnetization vs field curve. The extent of the hysteresis is an indication of the extent of flux pinning. If an electric current is introduced in the sample, once it exceeds some critical value the flux lines will begin to move, giving rise to an electrical resistance. So, the extent of the hysteresis is also related to the critical current, at which electrical resistance begins to appear.

If a paramagnetic or diamagnetic material is placed in an external, non-uniform, magnetic field, it experiences a force in the direction of the field gradient dH/dx . This force is directly proportional to the field gradient, and to M , the magnetization. If one can measure this force then, knowing the field gradient, the magnetization can be computed.

The theory and construction of an alternating gradient magnetometer has been described by Flanders⁶ and by the author. In the original design, the gradient field was swept sinusoidally and the force on the sample was measured using a piezoelectric transducer connected to a lock-in amplifier. In its present form the piezoelectric output is detected by a fast Fourier transform analyzer.

Apparatus

Magnetometer

A block diagram of the magnetometer and associated circuitry is shown in figure 1. The major components will be discussed separately in the following paragraphs. A complete description of the field coils and vane can be found in reference 7.

Wave Analyzer

The output of the piezoelectric transducer is processed by an Ono Sokki Mini FFT Analysis System. The FFT system is a small dedicated computer which performs a fast Fourier transform on the input signal and displays the wave spectrum in near real time. The amplitude of the peak corresponding to the driving frequency can be selected thereby eliminating other peaks caused by noise and overtones. The amplitude of the selected peak is read by the computer and stored in an array.

Function Generator

The driving current for the sweep coils is obtained from a Wavetek model 270 Function Generator. The drive voltage and frequency are input at the start of the program and written to the Wavetek by the computer. The frequency is set at the resonant frequency of the reed, or one of its overtones. The drive voltage is set to produce an rms current of 100 mA through the sweep coils.

Current Source

The current for the D.C. magnet is obtained from a Hewlett-Packard model 228A Current Source. The magnet current is ramped in steps of 0.10 Amp preceding each measurement of the signal amplitude. It was necessary to add a time delay of 2 to 4 seconds in order to allow the system to settle down between measurements. A further provision was added to allow the sample to be cooled initially in a preset magnetic field, in order to analyze the extent of flux pinning.

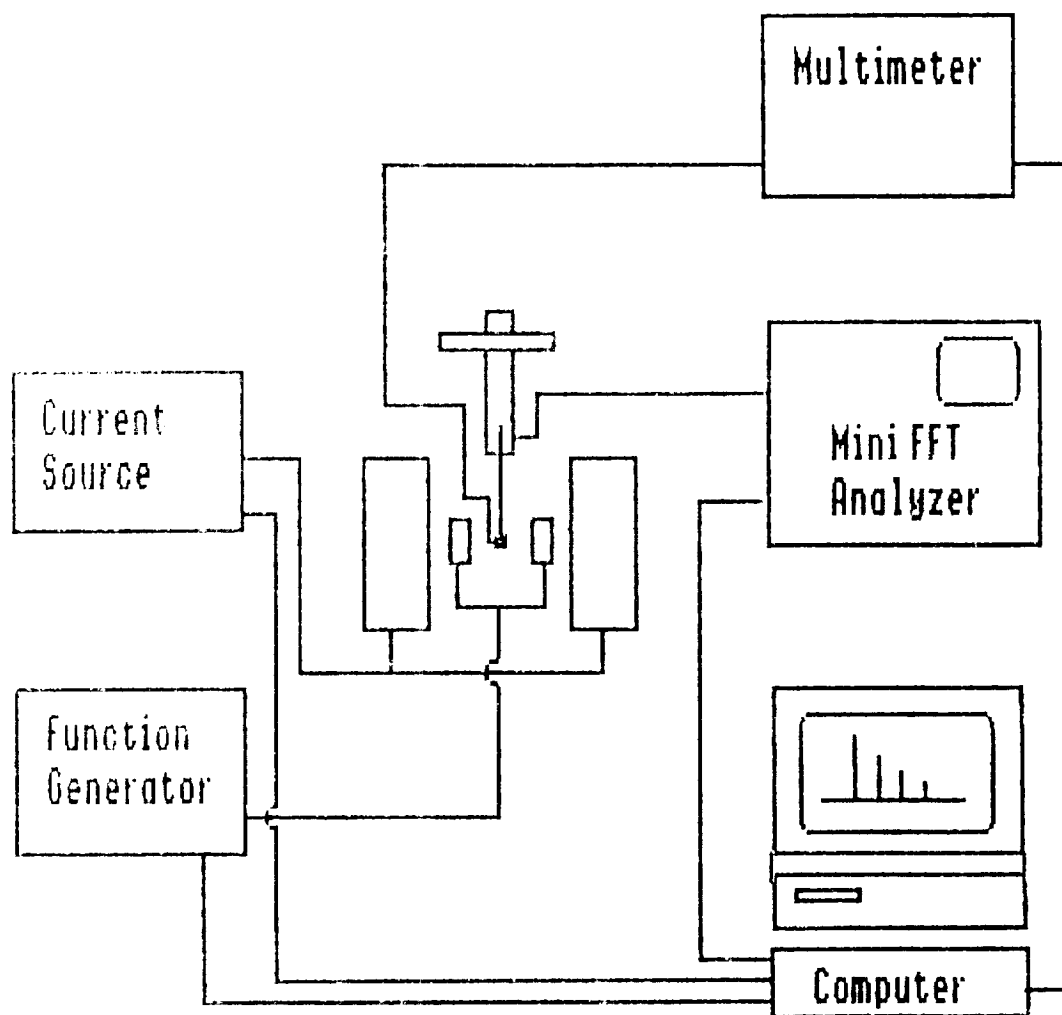


Figure 1. Magnetometer Block Diagram.

Computer

The HP 9133 computer was programmed in Basic to control the magnetometer and collect data on the magnetization, magnetic field, and temperature, through the GPIB bus. Data could be saved to disk and printed out or plotted. An HP 631 printer and an HP 7470A plotter were connected to the computer for these purposes.

Temperature Measurements

The temperature sensor is a Copper-Constantan thermocouple which is glued to the end of the vane, next to the sample, with GE 7031 varnish. The thermocouple output goes to an HP Model 3451A programmable multimeter. The thermocouple voltage is read by the computer and recorded as part of the data each time a measurement is made.

Programs

Four different variations of the Basic program were developed. (1) Magnitude, which measures the magnitude of the peak, at the sweep coil frequency, as a function of magnet current, from 0 to 1 A. (2) Cross Spectrum, which measures the real part of $A \times B$, where A is the sweep coil drive signal and B is the transducer output signal. The field current is swept from 1 A to -1 A. (3) Quick, which measures the magnitude at five values of magnet current, from 0 to 0.5 A and calculates the average slope and (4) TC, which records the magnetization and temperature as a sample is warmed through the superconducting transition. The flow chart in figure 2 applies to all three programs. The programs are menu driven. The first section initializes the four instruments and sets the operating parameters. The operator selects the frequency and voltage for the sweep coils, the input voltage range for the analyzer, and the gain for the display Y-axis. In program 1 the option of field cooling is provided as well. Following the initialization the subroutine "Acquire" is called which manages the actual acquisition of data. Once the data is taken, the subroutine "Store" is called and the data is stored on disk. The operator is prompted for a filename and may elect to not store the data at this point by doing a reset, in which case the data is lost. Once the data is stored on disk the menu provides options of plotting on the screen, printing on the screen, plotting on the plotter, or printing on the printer. Program listings are given in the Appendix.

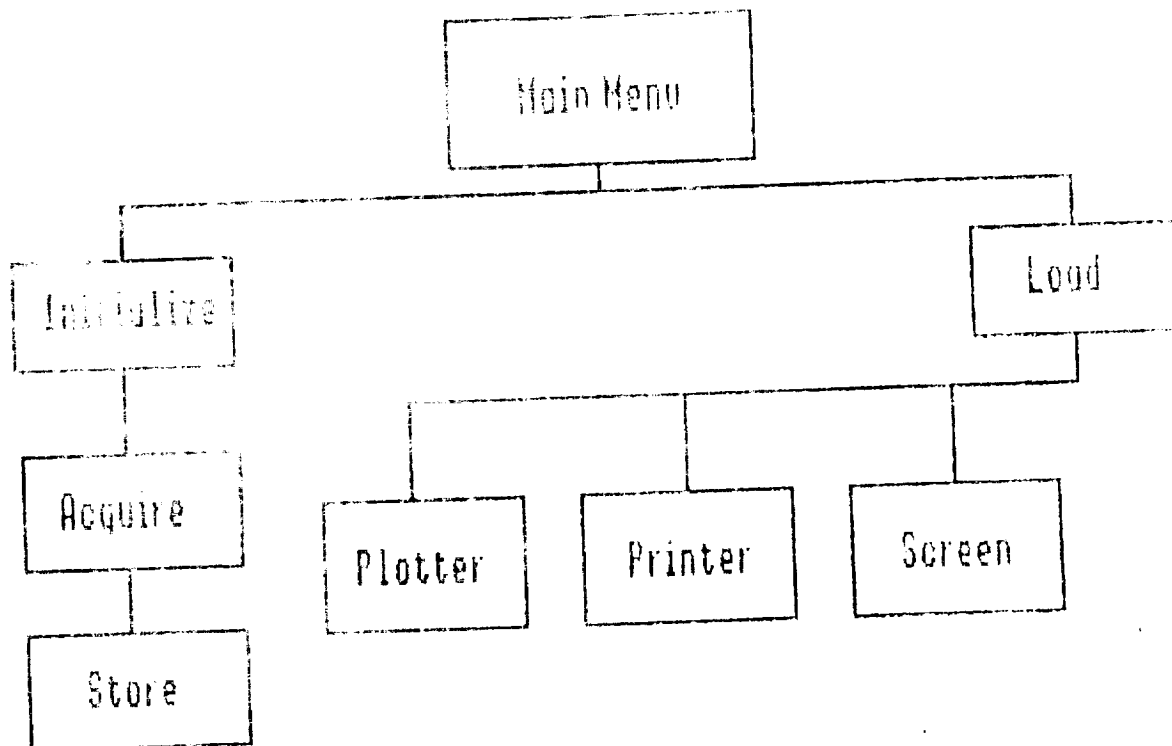


Figure 2. Program Flow Chart.

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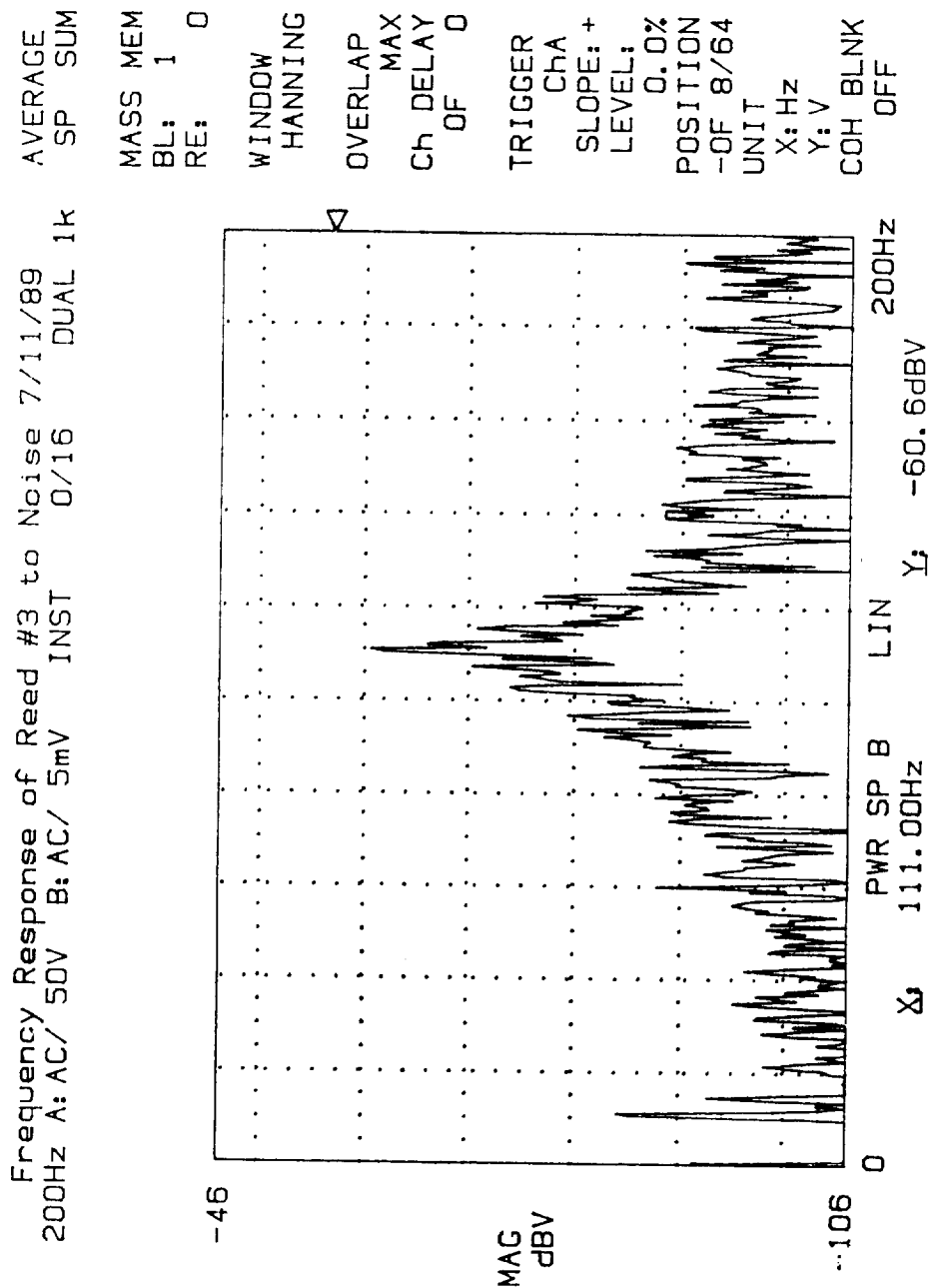
Results

Of the three types of piezoelectric transducers used, the PZT ceramic was found to give the most stable and reproducible results. This was largely due to the failure of the silver paint to properly bond the Kynar films to their copper supports. The response of the PZT reed to a white noise signal applied to the sweep coils is shown in Figure 3. This particular reed has a resonant frequency of 111 Hz. The peak at 10 Hz is due to vibrations of the isolation table on which the magnetometer was mounted. Figure 4 shows the response curve for an unsupported Kynar film. No resonance is seen, the 10 Hz noise peak is particularly large, followed by peaks at 60 and 180 Hz due to line noise. The response of this reed was nearly independent of frequency but was not nearly as good as that of the PZT reed near resonance. All of the following data were taken with the PZT reed.

Initially, two types of curves were generated. The curves of magnetization vs magnetic field, and curves of susceptibility vs temperature, which were generated by taking average slopes of the magnetization curves, fitted to straight lines. Figures 5 and 6 show a set of magnetization curves for $\text{Er}_1\text{Ba}_2\text{Cu}_3\text{O}_x$, the material which is referred to as Er123. The value of x is between 6.5 and 7 in the superconducting phase of this compound. In figure 5 the material is superconducting and diamagnetic while in figure 6 it is normal and paramagnetic, due to the Er ion in the lattice. The average slope of each curve was taken to determine the change in magnetic susceptibility with temperature, the result is shown in figure 7.

The degree of magnetic flux pinning can be determined by comparing magnetization curves for samples which have been field-cooled (Meissner effect) and zero-field cooled (shielding). If a sample is cooled below its superconducting critical temperature while in an applied magnetic field, the internal field is expelled, this is the Meissner effect. For type II materials, however, some magnetic flux can be pinned in the material and, for small fields, will not be expelled. This results in a positive contribution to the magnetization. Thus a difference in slope between field-cooled and zero-field cooled data on the same sample will give an indication of the extent of the flux pinning.

Figure 8 shows the magnetization vs magnetic field curves for a sample of Y123. The curves represent field-cooled ($H=27$ Oe) and zero-field cooled ($H=0$) conditions. The difference in slope between the two curves indicates the



DISPLAY 00:15
 FORMAT LIST 3-ARRAY COH BLK XFER P.OV INHIBIT EXIT

Figure 3. Frequency Response of the PZT Reed.

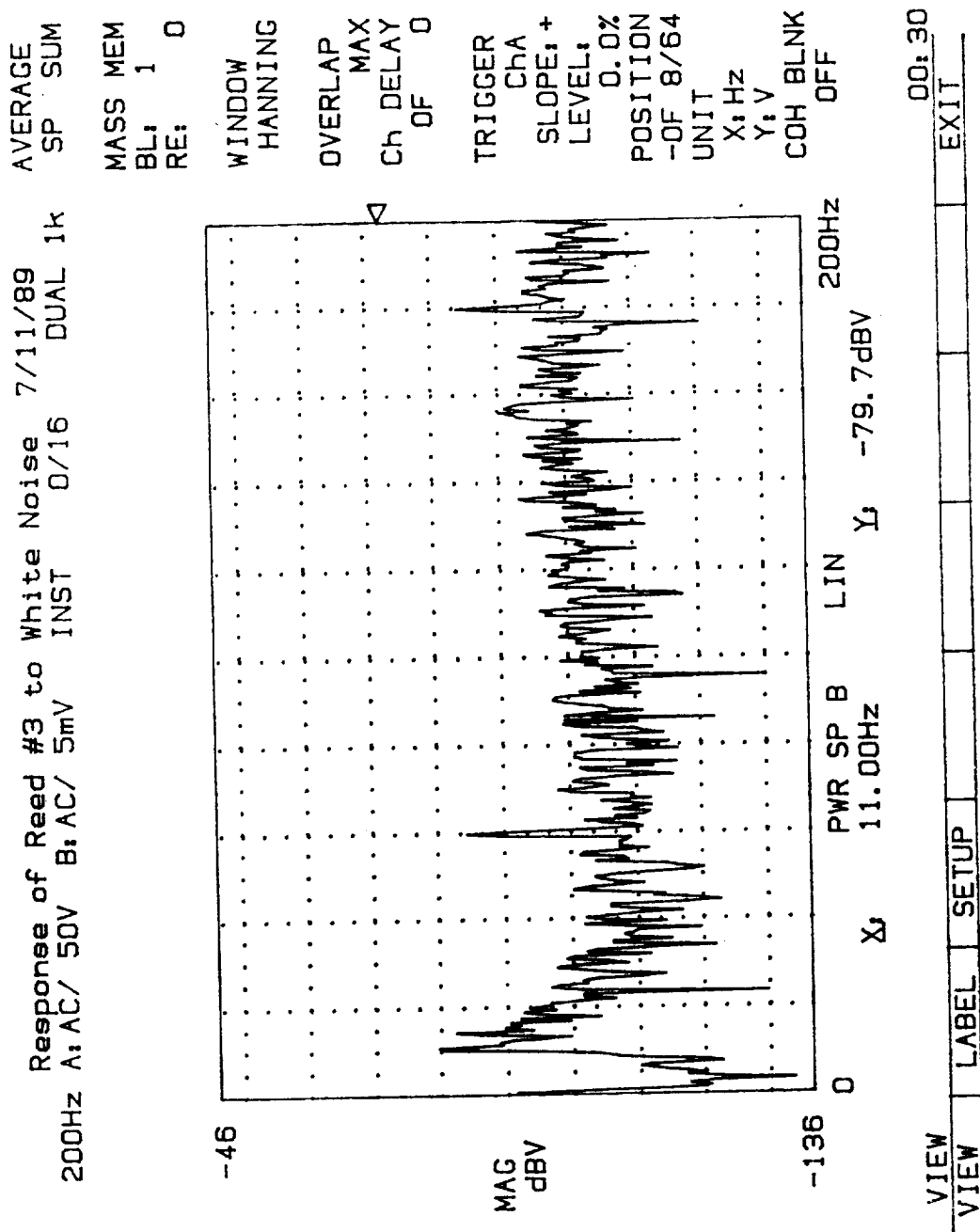


Figure 4. Frequency Response of Kynar Reed.

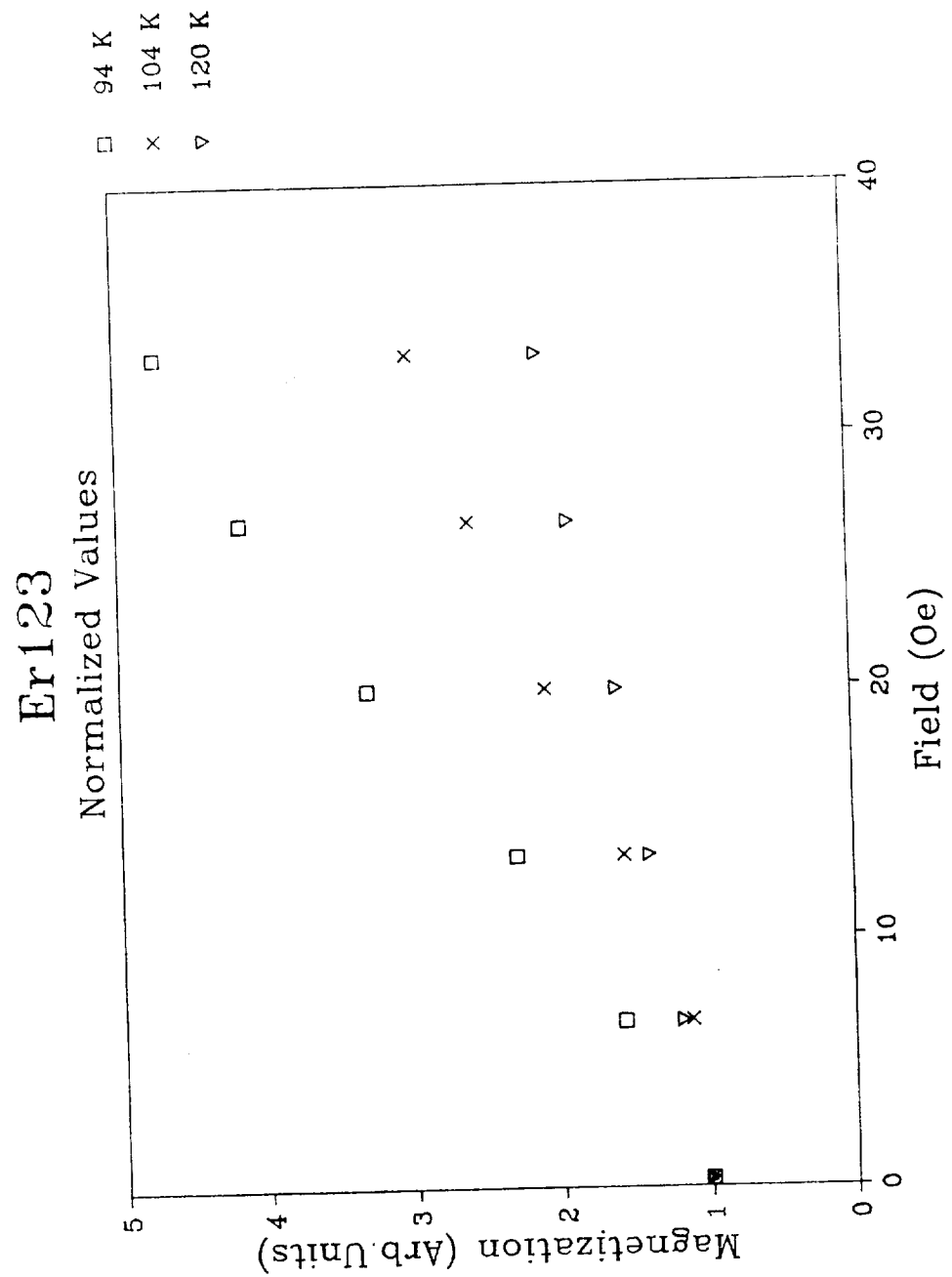


Figure 5. Magnetization Curve for Superconducting Er123.

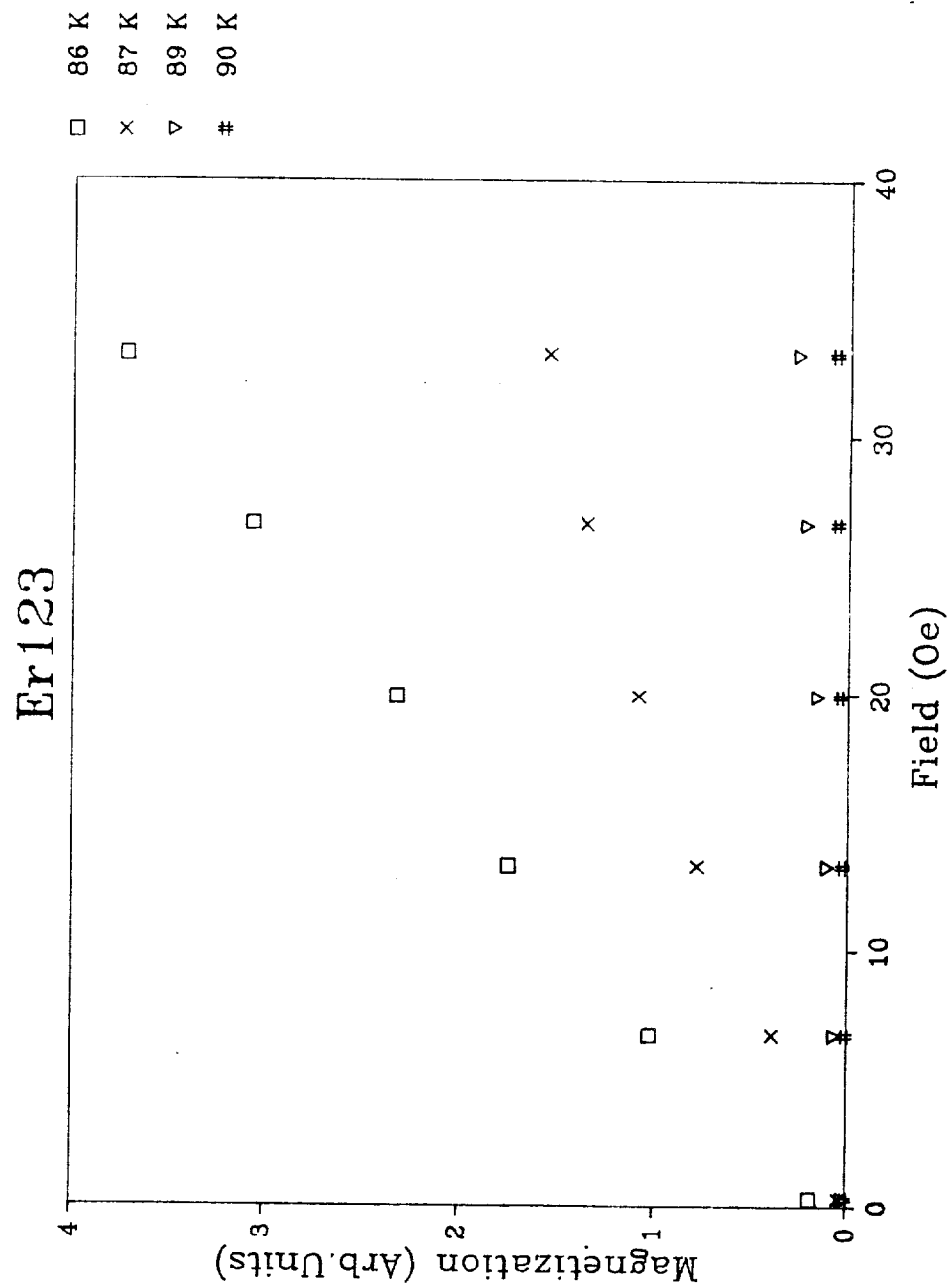


Figure 6. Magnetization Curve for Normal Er123.

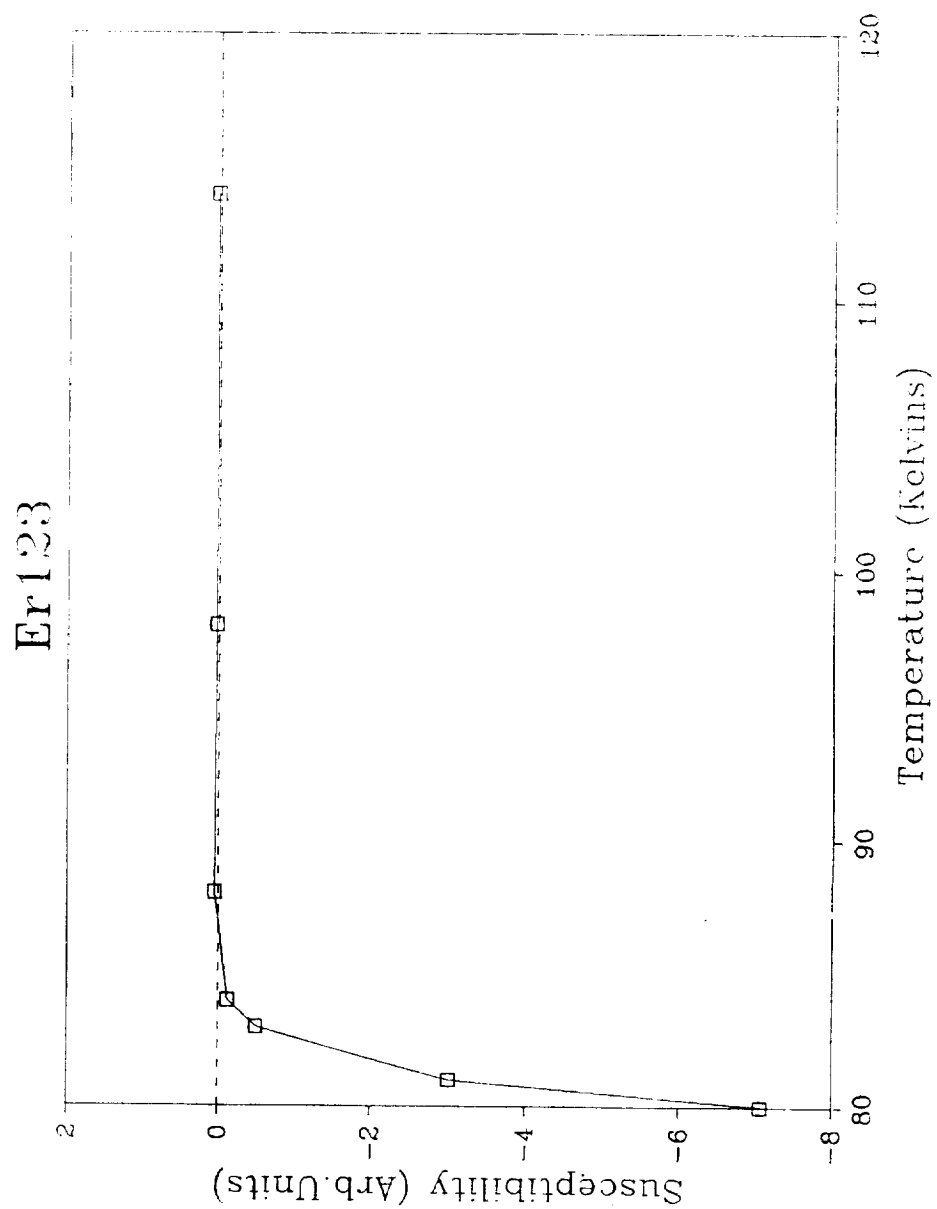


Figure 7. Susceptibility Curve for Er123.

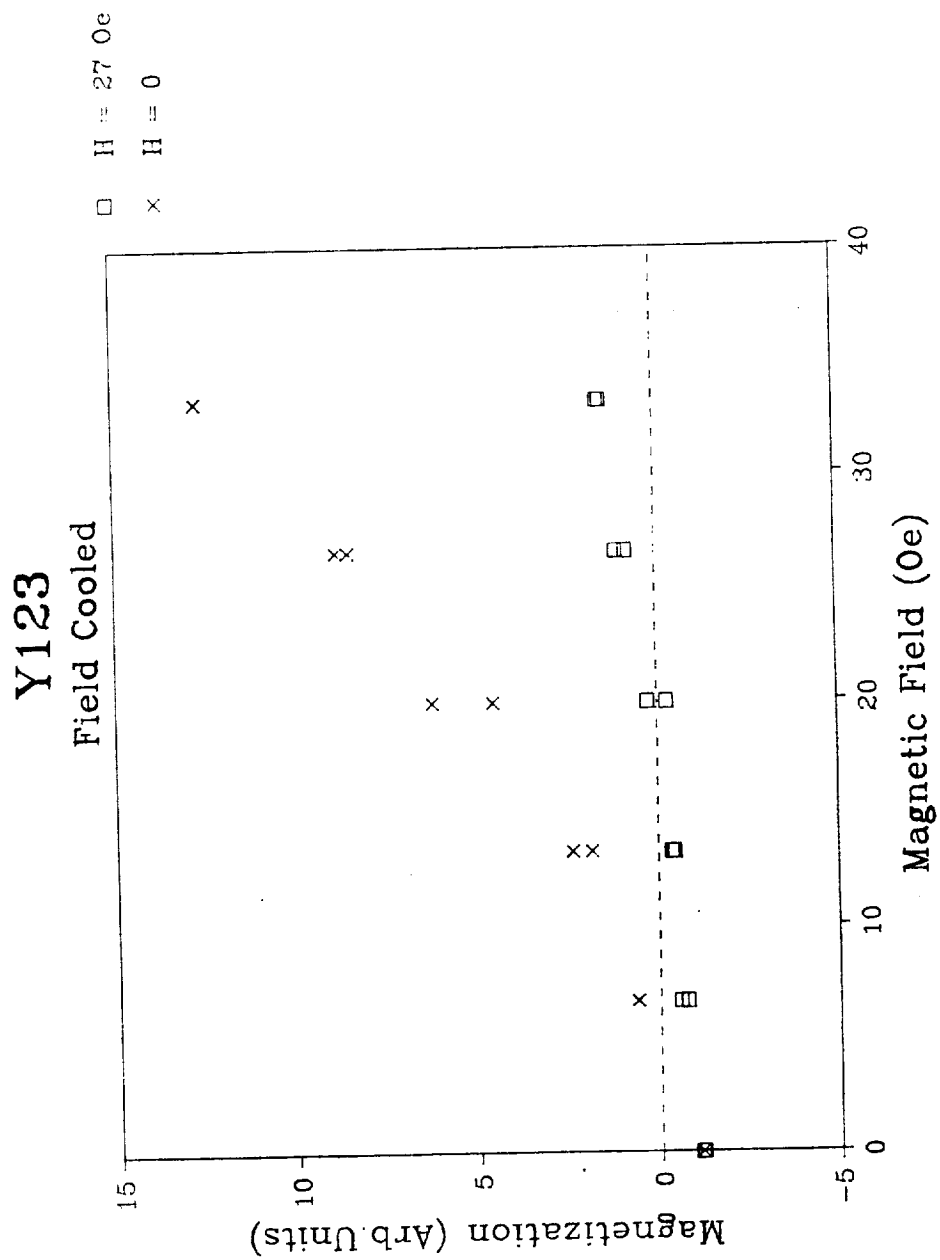


Figure 8. Magnetization Curve for Field-Cooled Y123.

extent of the flux pinning. Figure 9 shows the same experiment for Y123 which has been doped with Ag. Here the slopes of the two curves are practically identical, indicating little flux pinning in the doped material.

The program "Cross Spectrum" has the capability of distinguishing between positive and negative magnetization and can be used to generate hysteresis curves for magnetic materials. Figure 10 shows a hysteresis curve for a sample of Eu123+Ag which was zero-field cooled. The increase in (negative) magnetization on going once around the loop is a measure of the amount of trapped flux. The same sample is shown in figure 11 after field-cooling in a 66.4 Oe magnetic field. The curve is now closed, indicating that flux was trapped upon cooling.

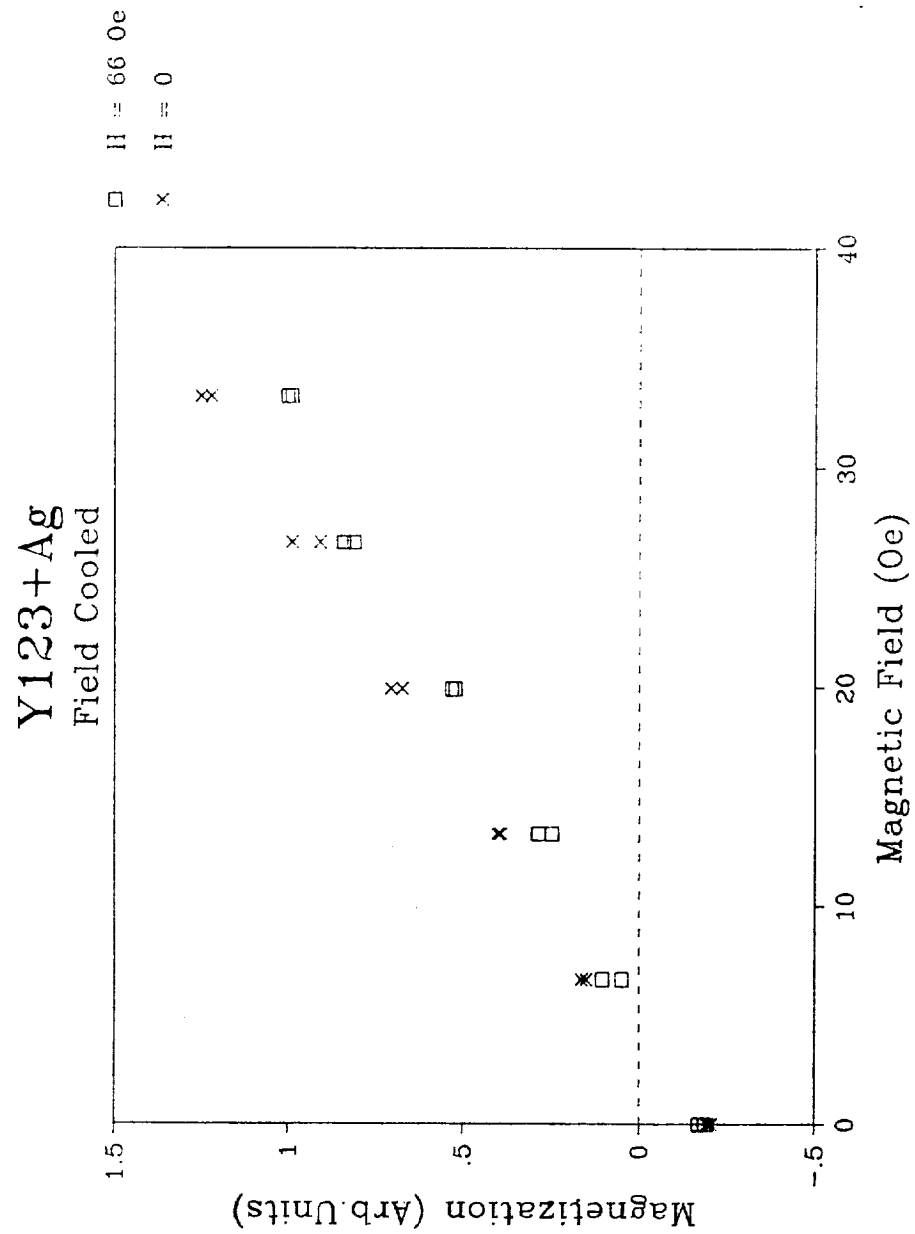


Figure 9. Magnetization Curve for Field-Cooled Y123+Ag.

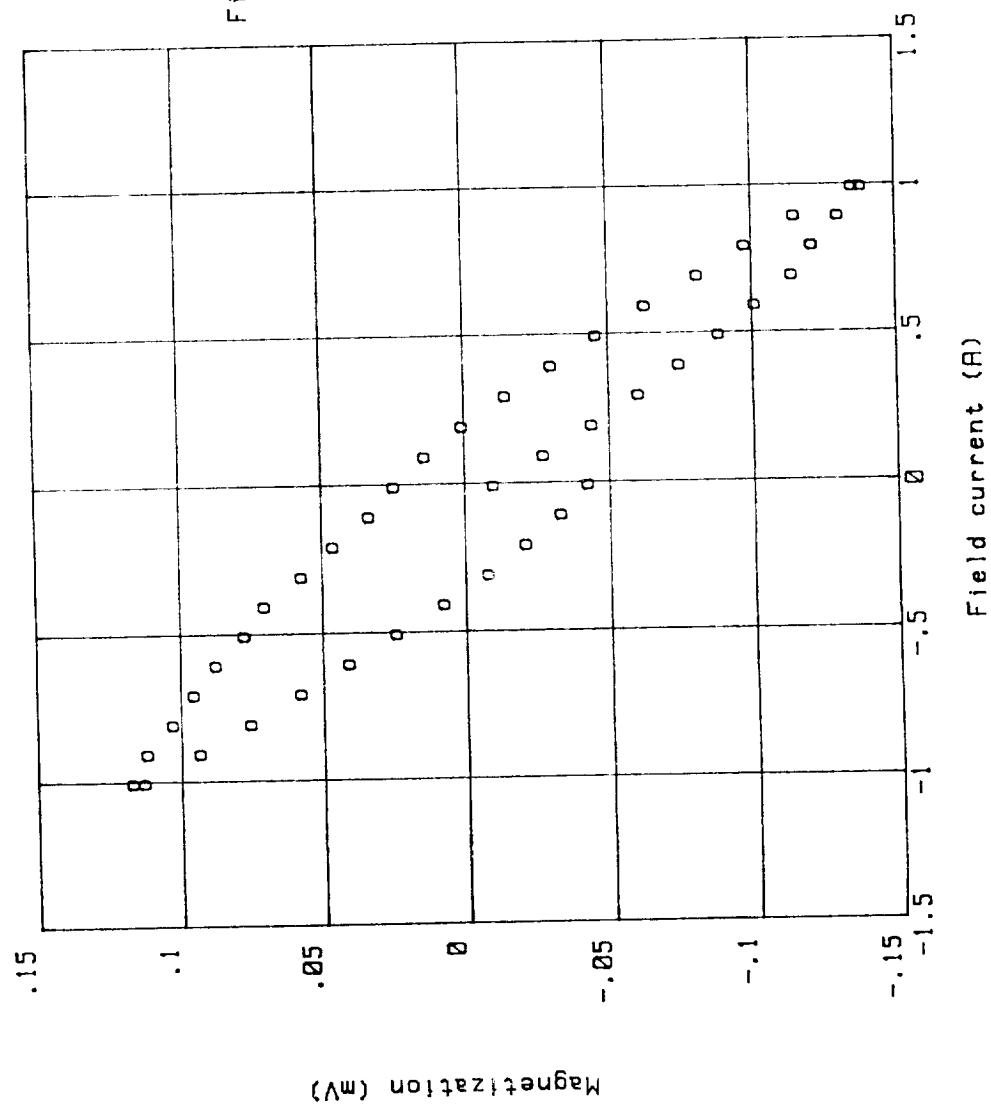


Figure 10. Hysteresis Loop for Eu123+AG.

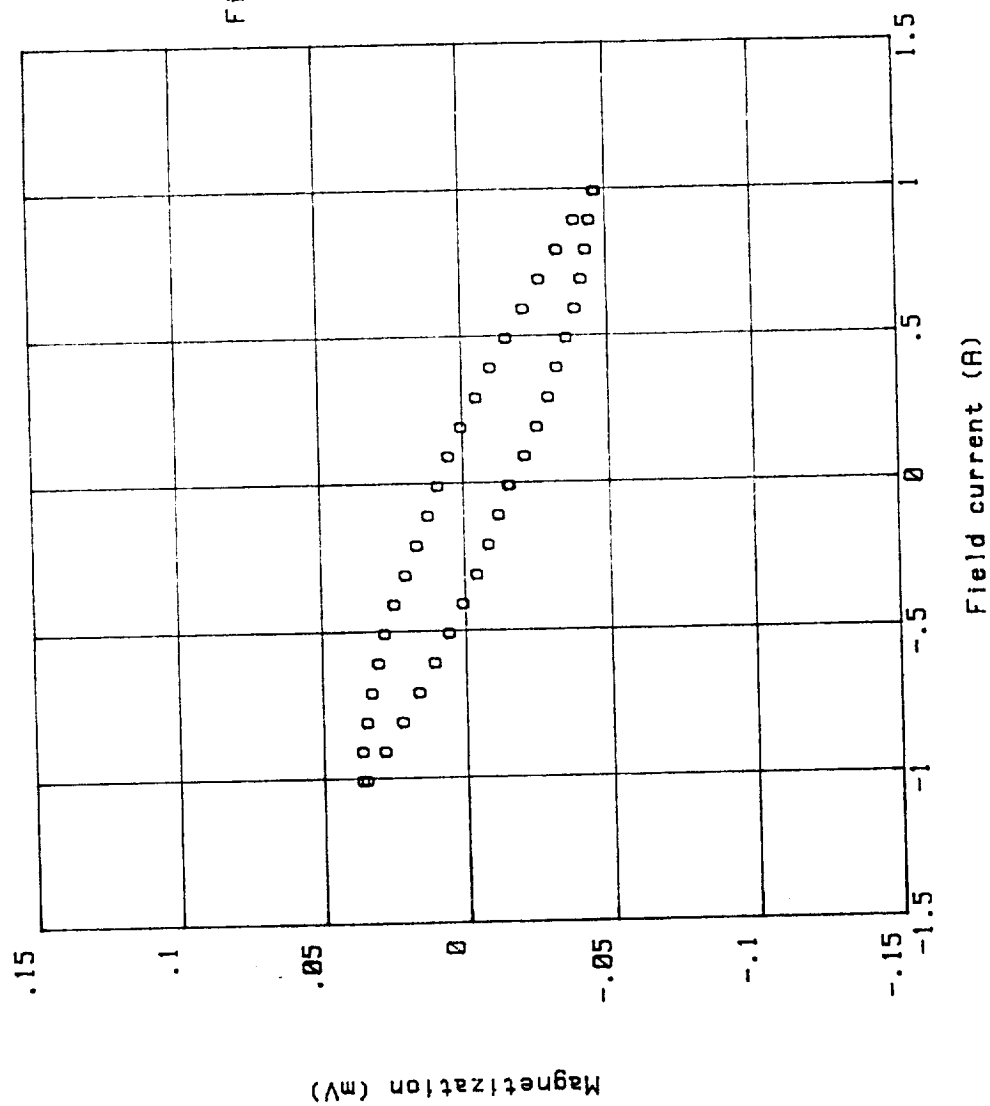


Figure 11. Hysteresis Loop for Field-Cooled Eu123+Ag.

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Conclusions and Recommendations

The alternating gradient magnetometer can be a valuable tool for the characterization of the magnetic properties of materials. It should be particularly useful in superconductivity research because of its sensitivity and ease of use. With the current data acquisition system, data may be taken more quickly than before and the data analysis is greatly simplified. The data which is acquired will become even more useful if the instrument is calibrated to measure magnetization in absolute units. This should not be difficult to do using a standard material, such as one of the rare-earth salts.

The chief difficulty in using this instrument is the lack of precise temperature control. The temperature of the sample changes with the liquid nitrogen level in the dewar. As the liquid evaporates the sample slowly warms. It would be convenient to be able to take a series of magnetization measurements at a fixed temperature. This is not possible with the current instrument although the rate of temperature change can be kept quite low, so that the temperature does not change more than about 0.1 K during the course of a measurement.

The computer program can be improved in several places. The program called Magnitude could be rewritten so that it would take a series of measurements, say one magnetization curve each degree of temperature change, and save them to disk automatically. The program called Cross Spectrum needs to have the temperature measuring routine added to it as well. Finally, some way needs to be devised to keep track of any variation in the resonant frequency of the reed and adjust the function generator accordingly.

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Appendix

```

10  ! *****!
20  ! PROGRAM: MAGNITUDE!
21  !
30  ! PLOTS THE MAGNITUDE OF THE SIGNAL ON CHANNEL B!
40  ! FROM ZERO TO 1/2 AMP MAGNET CURRENT!
50  ! USING THE CF-920 FFT ANALYSIS SYSTEM!
60  ! JUNE 8, 1989!
70  !
80  ! MODIFIED JULY 7, 1989 TO USE THE PZT TRANSDUCER!
81  ! MODIFIED JULY 17, 1989 TO MONITOR TEMPERATURE!
82  !
90  ! *****!
100 !
110 ! Number of Averages is in Line 580
120 !
130 OPTION BASE 1
140 CONTROL 1,12;1
150 DIM Magnitude(250),Fieldcurrent(250),Temperature(250)
160 PLOTTER IS 3,"INTERNAL"
170 GCLEAR
180 !
190 ! ***** MENU *****!
200 !
210 PRINT CHR$(12)
220 PRINT " (1) Acquire magnetization data"
230 PRINT
240 PRINT " (2) Load magnetization data from disc"
250 PRINT
260 PRINT " (3) Plot magnetization data on screen"
270 PRINT
280 PRINT " (4) Print magnetization data on screen"
290 PRINT
300 PRINT " (5) Plot magnetization data on plotter"
310 PRINT
320 PRINT " (6) Print magnetization data on printer"
330 INPUT Selection$
340 IF Selection$="1" THEN GOSUB Initialize
350 IF Selection$="2" THEN GOSUB Load
360 IF Selection$="3" THEN GOSUB Screenplot
370 IF Selection$="4" THEN GOSUB Screenprint
380 IF Selection$="5" THEN GOSUB Plotterplot
390 IF Selection$="6" THEN GOSUB Printerprint
400 GOTO 210 ! Clear Screen and Show Menu
410 Initialize: ! Setup Display Window
420 PLOTTER IS 3,"INTERNAL"
430 GINIT
440 GCLEAR
450 VIEWPORT 0,100,0,100
460 WINDOW 0,1,0,3
470 GRID .25,1
480 GRAPHICS ON
490 FRAME
500
510
520
530 ! ***** SET UP FOR CF920 *****!
540
550 INPUT "Channel B Range (1-15)",Br$
560 IF Br$="" THEN Br$="10"
570 OUTPUT 710;"AMS3" ! Spectrum peak averaging

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580 OUTPUT 710;"ANS5"           ! Take 5 squared averages
590 OUTPUT 710;"TRE"           ! Repeated trigger
600 OUTPUT 710;"TIA"           ! Channel a trigger
610 OUTPUT 710;"AAS2"          ! Channel A input voltage range
620 OUTPUT 710;"BAS"&Br$       ! Channel b input voltage range
630 OUTPUT 710;"FRS8"          ! Channel A&B input frequency range
640 OUTPUT 710;"BSP"           ! Display B spectrum
650 OUTPUT 710;"YLI"           ! Selects linear scaling
660 ! OUTPUT 710;"SON"          ! Search function on
670 ! OUTPUT 710;"SPS401"       ! Sets search marker for peak point
680
690 ***** CF920 SETUP COMPLETE *****
700
710
720
730 *****SETUP FOR THE 228 CURRENT SOURCE*****
740
750 CLEAR 711
760 OUTPUT 711;"V25"           ! Voltage limits to 25 volts
770 INPUT "Initial Current (0-1)",Current ! Used for Field Cooling
780 IF Current=0 THEN GOTO 810
790 OUTPUT 711;"I"&VAL$(Current)
800 GOTO 820
810 OUTPUT 711;"I0"           ! Initializes current to 0 amperes
820 OUTPUT 711;"F1X"           ! Execute
830 INPUT "Press a Key to Continue",K$
840 ***** SETUP FOR THE 228 CURRENT SOURCE COMPLETE *****
850
860 ***** SETUP FOR HP3457A TO READ TEMPERATURE *****
870 ! USING A COPPER-CONSTANTAN THERMOCOUPLE !
880 !
890 ! INTEGER I
900 ASSIGN @Temp TO 724
910 OUTPUT @Temp;"TRIG SYN"
920 OUTPUT @Temp;"NDIG 4"      ! Four Digit Accuracy
930 OUTPUT @Temp;"FIXEDZ OFF"
940 OUTPUT @Temp;"DCV"         ! Read DC Volts
950 OUTPUT @Temp;"AZERO 1"     ! Automatic Zero
960 OUTPUT @Temp;"NPLC 10"     ! Ten Power Line Cycle Delay
970 !
980 ***** TEMPERATURE SETUP COMPLETE *****
990 !
1000 ***** SETUP FOR THE 270 *****
1010 !
1020 Rf$="100"                 ! Resonant frequency of PZT
1030 Swv$="4.40"              ! Sweep voltage of little coils
1040 PRINT CHR$(12)           ! Clears screen
1050 CLEAR 709
1060 INPUT "Resonant frequency",Trf$
1070 IF Trf$="" THEN
1080     Rf$=Rf$               ! Default value is 74.4 Hz
1090 ELSE
1100     Rf$=Trf$
1110 END IF
1120 INPUT "Sweep voltage",Tswv$
1130 IF Tswv$="" THEN
1140     Swv$=Swv$             ! Default value is 4.4 volts
1150 ELSE
1160     Swv$=Tswv$
1170 END IF

```

```

1180 Freq=VAL(Rf$)
1190 Rf$="F"&Rf$ ! Adds a F for frequency to variable
1200 OUTPUT 709;Rf$ ! Sets frequency of Wavetek
1210 OUTPUT 709;"I" ! Execute
1220 Swv$="A"&Swv$ ! Adds an A for amplitude to variable
1230 OUTPUT 709;Swv$ ! Sets voltage for Wavetek
1240 OUTPUT 709;"I" ! Execute
1250 OUTPUT 709;"P1" ! Output on
1260 OUTPUT 709;"I" ! Execute
1270 OUTPUT 709;"TSI" ! Displays frequency on front of 270
1280 OUTPUT 709;"F"
1290 !
1300 !***** ENABLE CF920 DELTA SEARCH FUNCTION *****!
1310 !
1320 OUTPUT 710;"SON" ! SEARCH ON
1330 Hf=(Freq)*2+5 ! UPPER LIMIT OF SEARCH
1340 Lf=(Freq)*2-5 ! LOWER LIMIT OF SEARCH
1350 Lf$=VAL$(Lf)
1360 Hf$=VAL$(Hf)
1370 OUTPUT 710;"SPS"&Lf$ ! SET LOWER LIMIT
1380 OUTPUT 710;"DON" ! DELTA FUNCTION ON
1390 OUTPUT 710;"DCS" ! SET THE DELTA CURSOR
1400 OUTPUT 710;"SPS"&Hf$ ! SET UPPER LIMIT
1410 INPUT "Y-AXIS GAIN (1-5)",Yag
1420 FOR G=1 TO Yag
1430 OUTPUT 710;"YGU"
1440 NEXT G
1450 OUTPUT 710;"PAO" ! PARTIAL OVERALL ON
1460 !
1470 !***** SETUP FOR THE 270 WAVETEK COMPLETE *****!
1480 !
1490 !
1500 !
1510 GOSUB Acquire ! Take data
1520 !*****
1530 GOSUB Store ! Write the data to disc
1540 RETURN ! Back to the Menu
1550 STOP
1560 Acquire: ! Take data *****
1570 I=0
1580 FOR Fieldi=0 TO .5 STEP .1 ! 0 to 0.5 Amps in 5 steps
1590 IF Fieldi<1.E-9 AND Fieldi>-1.E-9 THEN Fieldi=0
1600 I=I+1
1610 Fieldi$="I"&VAL$(Fieldi) ! Adds an I to the field current vairable
1620 OUTPUT 711;Fieldi$ ! Sends value of current to current source
1630 OUTPUT 711;"F1X" ! Execute
1640 WAIT 3 ! Wait for system to settle
1650 OUTPUT 710;"LYS" ! Selects Display Y search value
1660 ENTER 710;Volts ! Reads display Y search value ; volts
1670 Magnitude(I)=Volts
1680 Fieldcurrent(I)=Fieldi
1690 GOSUB Plot ! Plot data on the screen
1700 NEXT Fieldi
1710 FOR Fieldi=.5 TO 0 STEP -.1 ! .5 to 0 amps
1720 IF Fieldi<1.E-9 AND Fieldi>-1.E-9 THEN Fieldi=0
1730 I=I+1
1740 Fieldi$="I"&VAL$(Fieldi) ! Adds an I to the field current vairable
1750 OUTPUT 711;Fieldi$ ! Sends value of current to current source
1760 OUTPUT 711;"F1X" ! Execute
1770 WAIT 3 ! Wait for system to settle

```

```

1780      OUTPUT 710;"LYS"      ! Selects display Y search value
1790      ENTER 710;Volts      ! Reads display Y search value
1800      Magnitude(I)=Volts
1810      Fieldcurrent(I)=FieldI
1820      GOSUB Plot            ! Show data point on screen
1830      NEXT FieldI
1840      ENTER @Temp;Voltage    ! Read the Temperature
1850      Volts=Voltage*1000     ! Convert to Millivolts
1860      GOSUB Temperature     ! Calculate the Temperature
1870      OUTPUT 711;"FOX"      ! Put Current Source on Standby
1880      CLEAR 709
1890      OUTPUT 710;"PAF"      ! DISABLE PARTIAL OVERALL
1900      OUTPUT 710;"DOF"      ! DISABLE DELTA SEARCH
1910      OUTPUT 710;"SOF"      ! DISABLE SEARCH FUNCTION
1920      CLEAR 710
1930      RETURN                ! From ACQUIRE
1940 Plot:      ! Plot data points on the screen *****
1950      LOG 5                  ! Label origin at center
1960      MOVE Fieldcurrent(I),Magnitude(I)
1970      LABEL "*"              ! Plot using asterisks
1980      PRINT I,Fieldcurrent(I),Magnitude(I)
1990      RETURN
2000 Store:      ! Store the data in a disc file *****
2010      N=I
2020      REDIM Magnitude(N),Fieldcurrent(N)
2030      GRAPHICS OFF
2040      ALPHA ON
2050      PRINT CHR$(12)         ! Clear screen
2060      INPUT "File name ?",File$
2070      CREATE BDAT File$,INT(N*8/256)+2
2080      ASSIGN @Path TO File$
2090      OUTPUT @Path;N,Temp,Magnitude(*),Fieldcurrent(*)
2100      ASSIGN @Path TO *
2110      RETURN                ! From STORE
2120 Load:      !
2130      PRINT CHR$(12)         ! Clear screen
2140      Controller=1
2150      CAT;NAMES              ! Display catalog filenames
2160      INPUT "Enter file name to be loaded from above list.",File$
2170      IF File$="" THEN 2240   ! Return if no entry
2180      ASSIGN @Track TO File$
2190      ENTER @Track;N         ! Number of data points
2200      ENTER @Track;Temp
2210      REDIM Magnitude(N),Fieldcurrent(N)
2220      ENTER @Track;Magnitude(*),Fieldcurrent(*)
2230      ASSIGN @Track TO *     ! Close the file
2240      RETURN                ! From LOAD
2250 Screenprint: ! Print the data on the screen
2260      IF Controller=0 THEN
2270          DISP "LOAD A FILE FIRST!!!"
2280          GOTO 2480
2290      END IF
2300      PRINT "Filename = ";File$
2310      PRINT "Temperature = ";Temp
2320      FOR I=1 TO N
2330          PRINT I,Magnitude(I),Fieldcurrent(I)
2340      NEXT I
2350      FOR K=1 TO 4
2360          Mag(K)=Magnitude(K+1)-Magnitude(1) ! Calculate slope
2370      NEXT K

```

```

2380 Sum=0
2390 FOR K=1 TO 4
2400 Sum=Sum+Mag(K)
2410 NEXT K
2420 Slope=Sum/.5 ! Average slope of first 5 points
2430 PRINT
2440 PRINT "Initial Slope = ";Slope
2450 DISP "Hit CONTINUE to continue program."
2460 PAUSE
2470 Controller=0
2480 RETURN ! From SCREENPRINT
2490 !
2500 Printerprint: ! Send data to the printer
2510 PRINTER IS 701
2520 GOSUB Screenprint
2530 PRINTER IS 1
2540 RETURN ! From PRINTERPRINT
2550 !
2560 Screenplot: ! Plot the full graph on the screen
2570 PRINT CHR$(12) ! Clear screen
2580 GCLEAR ! Clear graphic screen
2590 GRAPHICS OFF
2600 ALPHA ON
2610 GOSUB Sort ! Find min and max values
2620 GRAPHICS ON
2630 ALPHA OFF
2640 Yinta=Yint-(Maxy-Miny)/75
2650 Xinta=Xint-(Maxx-Minx)/75
2660 VIEWPORT 20,100,12,92
2670 FRAME
2680 WINDOW Minx,Maxx,Miny,Maxy
2690 AXES Xtic,Ytic,Minx,Miny,1,1,2
2700 PEN 1
2710 LORG 6 ! Label origin above character
2720 GRID Xtic,Ytic ! Draw a grid
2730 CLIP OFF
2740 CSIZE 3,.5 ! Character size/aspect ratio
2750 FOR I=Minx TO Maxx+Xtic/100 STEP Xtic
2760 MOVE I,Miny ! X-axis numbers
2770 IF ABS(I)<1.E-15 THEN
2780 J=0
2790 LABEL J
2800 GOTO 2830
2810 END IF
2820 LABEL I
2830 NEXT I
2840 LORG 7 ! Label origin lower right
2850 FOR I=Miny TO Maxy+Ytic/100 STEP Ytic
2860 MOVE Minx,I ! Y-axis numbers
2870 IF ABS(I)<1.E-15 THEN
2880 J=0
2890 LABEL J
2900 GOTO 2930
2910 END IF
2920 LABEL I
2930 NEXT I
2940 LORG 5 ! Label origin to center
2950 PEN 2 ! Pen for data points
2960 FOR I=1 TO N
2970 MOVE Fieldcurrent(I),Magnitude(I)

```



```

2980 LABEL "o" ! Character for points
2990 NEXT I
3000 PEN 1
3010 VIEWPORT 20,100,15,95
3020 WINDOW 20,100,15,95
3030 CLIP OFF
3040 MOVE 60,5 ! Position of X-axis label
3050 LORG 5
3060 LDIR 0 ! Horizontal
3070 LABEL "Field current (A)" ! X-axis label
3080 MOVE 5,55 ! Position of Y-axis label
3090 DEG ! Use degrees
3100 LDIR 90 ! Orient vertically
3110 LORG 5 ! Center
3120 LABEL "Magnetization (mV) " ! Y-axis label
3130 LDIR 0 ! Horizontal
3140 MOVE 115,75 ! Position for sidebar
3150 LABEL Title$ ! Sidebar header
3160 LABEL "Temp. = ";Temp
3170 LABEL "Filename = ";File$
3180 LABEL TIME$(TIMEDATE) ! Time
3190 LABEL DATE$(TIMEDATE) ! Date
3200 RETURN ! from SCREENPLOT
3210 !
3220 Sort: ! Get max and min
3230 Minx=MIN(Fieldcurrent(*))
3240 Maxx=MAX(Fieldcurrent(*))
3250 Miny=MIN(Magnitude(*))
3260 Maxy=MAX(Magnitude(*))
3270 PRINT "Fieldcurrent ranges from";Minx;"to";Maxx
3280 PRINT
3290 PRINT "Magnetization ranges from";Miny;"to";Maxy
3300 PRINT
3310 INPUT "Input (Minx,Maxx,Miny,Maxy) to be plotted",Minx,Maxx,Miny,Maxy
3320 PRINT
3330 PRINT "Fieldcurrent plot ranges from";Minx;"to";Maxx
3340 PRINT
3350 PRINT "Magnetization ranges plot from";Miny;"to";Maxy
3360 PRINT
3370 INPUT "Input tick mark spacing and axes intercepts (Xtic,Ytic,Xint,Yint)",Xtic,Ytic,Xint,Yint
3380 PRINT
3390 INPUT "Title for graph",Title$ ! Sidebar title
3400 RETURN ! From SORT
3410 !
3420 Plotterplot: ! Send plot data to plotter
3430 PLOTTER IS 705,"HPGL"
3440 GOSUB Screenplot
3450 RETURN ! From PLOTTERPLOT
3460 Temperature: ! Calculate the Temperature from Thermocouple Voltage
3470 LET V=Volts
3480 IF V>=-5.602 AND V<=-5.439 THEN
3490 Temp=73+61.109*(V+5.603)
3500 END IF
3510 IF V>=-5.439 AND V<=-5.261 THEN
3520 Temp=83+58.602*(V+5.439)
3530 END IF
3540 IF V>=-5.261 AND V<=-5.069 THEN
3550 Temp=93+54.159*(V+5.261)
3560 END IF

```

```

3570 IF V>-5.069 AND V<-4.865 THEN
3580 Temp=103+50.596*(V+5.069)
3590 END IF
3600 IF V>-4.865 AND V<-4.468 THEN
3610 Temp=113+47.587*(V+4.865)
3620 END IF
3630 IF V>=-4.468 THEN           ! Just report the voltage
3640 Temp=V
3650 END IF
3652 PRINT Temp                ! From Temperature
3660 RETURN
3670 END

```